

# Electrical Engineering 1

12026105

Chapter 8

Second-Order Circuits

## Learning Objectives

*By using the information and exercises in this chapter you will be able to:*

1. Develop a better understanding of the solution of general-second order differential equations.
2. Learn how to determine initial and final values.
3. Understand the response in source-free series *RLC* circuits.
4. Understand the response in source-free parallel *RLC* circuits.
5. Understand the step response of series *RLC* circuits.
6. Understand the step response of parallel *RLC* circuits.
7. Understand general second-order circuits.
8. Understand general second-order circuits with op amps.

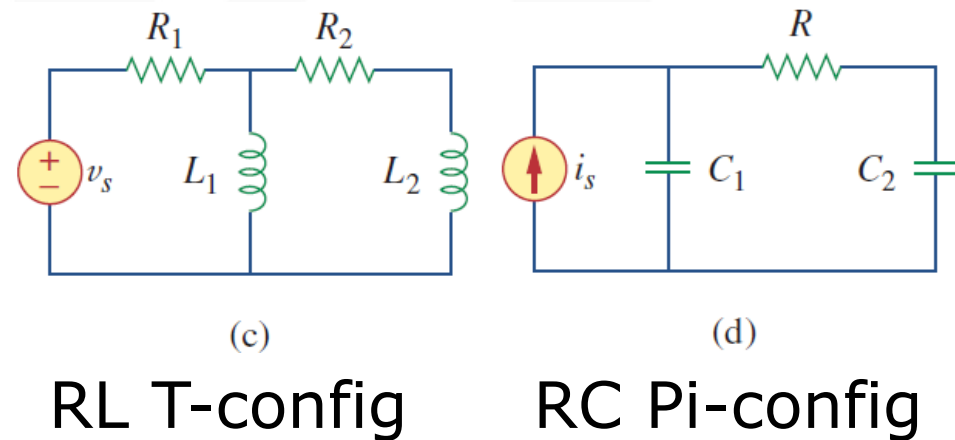
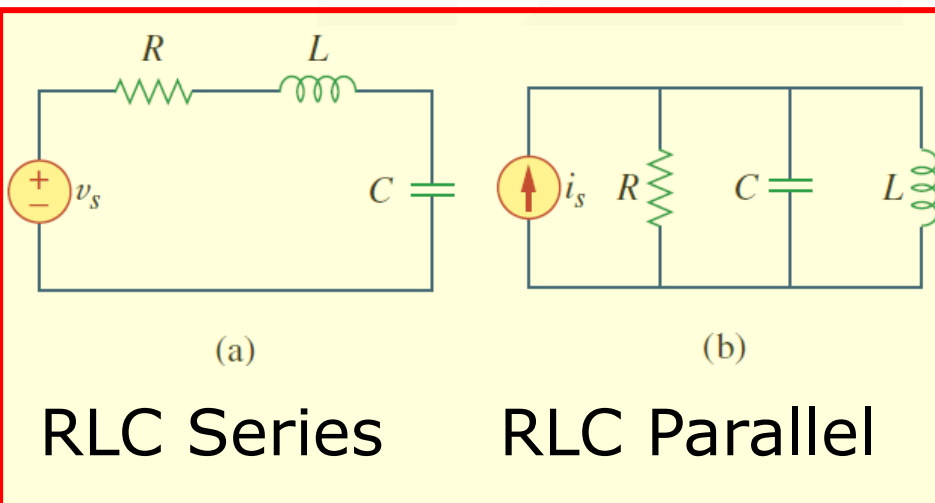
# Second-Order Circuits Chapter 8

- 8.1 Examples of 2<sup>nd</sup> order RCL circuit
- 8.2 The source-free series RLC circuit
- 8.3 The source-free parallel RLC circuit
- 8.4 Step response of a series RLC circuit
- 8.5 Step response of a parallel

# 8.1 Second Order RLC circuits (1)

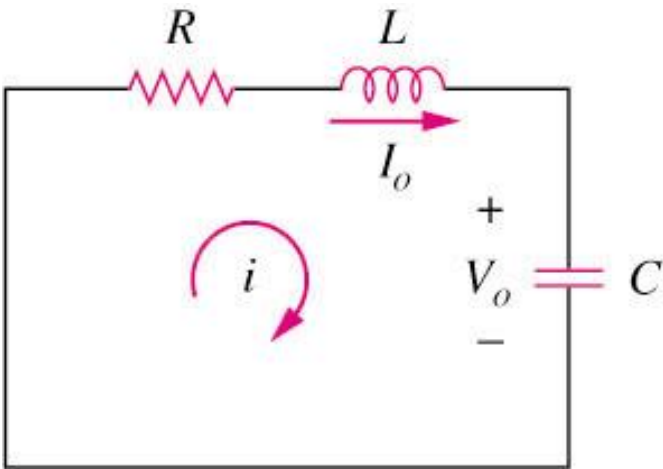
## What is a 2nd order circuit?

A second-order circuit is characterized by a second-order differential equation. It consists of resistors and the equivalent of two energy storage elements.



# 8.2 Source-Free Series RLC Circuits

- The solution of the source-free series RLC circuit is called as the natural response of the circuit.
- The circuit is excited by the energy initially stored in the capacitor and inductor.

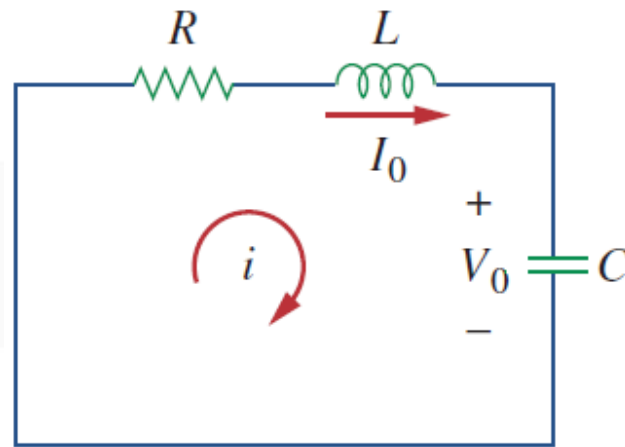


The 2<sup>nd</sup> order  
of expression

$$\frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{i}{LC} = 0$$

## How to derive and how to solve?

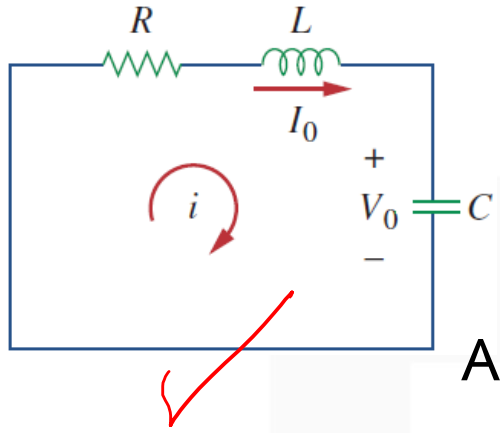
# 8.2 Source-Free Series RLC Circuits



*For Capacitor :*  $v(0) = v(0^+) = v(0^-) = V_0$

*For Inductor :*  $i(0) = i(0^+) = i(0^-) = I_0$

# 8.2 Source-Free Series RLC Circuits



Initial Conditions

①  $i(0) = I_0$

②  $v(0) = \frac{1}{C} \int_{-\infty}^0 i dt = V_0$

Apply KVL

$Ri + L \frac{di}{dt} + \frac{1}{C} \int_{-\infty}^t i dt = 0$

$R \frac{di}{dt} + L \frac{d^2i}{dt^2} + \frac{i}{C} = 0$

$\frac{d^2i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{i}{LC} = 0$

$V_c = L \frac{di}{dt}$

To solve such a 2<sup>nd</sup> order diff eq. We need 2 initial conditions, such as  $i(0)$  and  $\frac{di(0)}{dt}$  (from  $v(0)$ )

$I_0$        $V_0$

# 8.2 Source-Free Series RLC Circuits

We get the initial value of the derivative of  $I$  from equation after applying KVL; that is,

$$\underline{Ri(0)} + L \frac{\underline{di(0)}}{dt} + \underline{v(0)} = 0$$

$$RI_0 + L \frac{di(0)}{dt} + V_0 = 0$$

$V_0$

$$\frac{di(0)}{dt} = -\frac{1}{L}(RI_0 + V_0)$$

2 Initial Conditions

$$i(0) = I_0$$



# 8.2 Source-Free Series RLC Circuits

In 1<sup>st</sup> order circuits suggests that the solution is  $I_0 e^{-t/\tau}$ . So we let

$i = Ae^{st}$  Where  $A$  and  $s$  have to be determined

$$\frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{i}{LC} = 0$$

$$As^2 e^{st} + \frac{AR}{L} s e^{st} + \frac{Ae^{st}}{LC} = 0 \quad \rightarrow \quad Ae^{st} \left( s^2 + \frac{R}{L} s + \frac{1}{LC} \right) = 0$$

~~$$Ae^{st} = 0$$~~

$$s^2 + \frac{R}{L} s + \frac{1}{LC} = 0$$

*a*
*b*
*c*

$$s_{1,2} = \frac{-\frac{R}{L} \pm \sqrt{\left(\frac{R}{L}\right)^2 - \frac{4}{LC}}}{2} = -\frac{R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}$$

# 8.2 Source-Free Series RLC Circuits

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}$$

$$s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$$

$$\alpha = \frac{R}{2L} \quad \text{and} \quad \omega_0 = \frac{1}{\sqrt{LC}}$$

$$s^2 + \alpha s + \omega_0^2 = 0$$

$$i = A e^{st} \rightarrow A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$i(t) = \underline{A_1} e^{s_1 t} + \underline{A_2} e^{s_2 t}$$

# 8.2 Source-Free Series RLC Circuits

$$z = a + bj \Rightarrow 3 + 2j$$

There are 3 possible solutions for the following 2<sup>nd</sup> order differential equation:

$$\sqrt{-1} = j$$

$$\frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{i}{LC} = 0$$

$$i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$s_1 \rightarrow \alpha, \omega_0$

$$\Rightarrow \frac{d^2 i}{dt^2} + 2\alpha \frac{di}{dt} + \omega_0^2 i = 0$$

$$\text{Where } \alpha = \frac{R}{2L} \text{ and } \omega_0 = \sqrt{\frac{1}{LC}}$$

General 2<sup>nd</sup> order Form

$$s_1 = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

The types of solutions for  $i$  depend on the relative values of  $\alpha$  and  $\omega_0$

# 8.2 Source-Free Series RLC Circuits

$$i(t) = I_0 e^{-t/\tau}$$

There are 3 possible solutions for the following 2<sup>nd</sup> order differential equation:

$$\frac{d^2i}{dt^2} + 2\alpha \frac{di}{dt} + \omega_0^2 i = 0$$

1. If  $\alpha > \omega_0$ , over-damped case

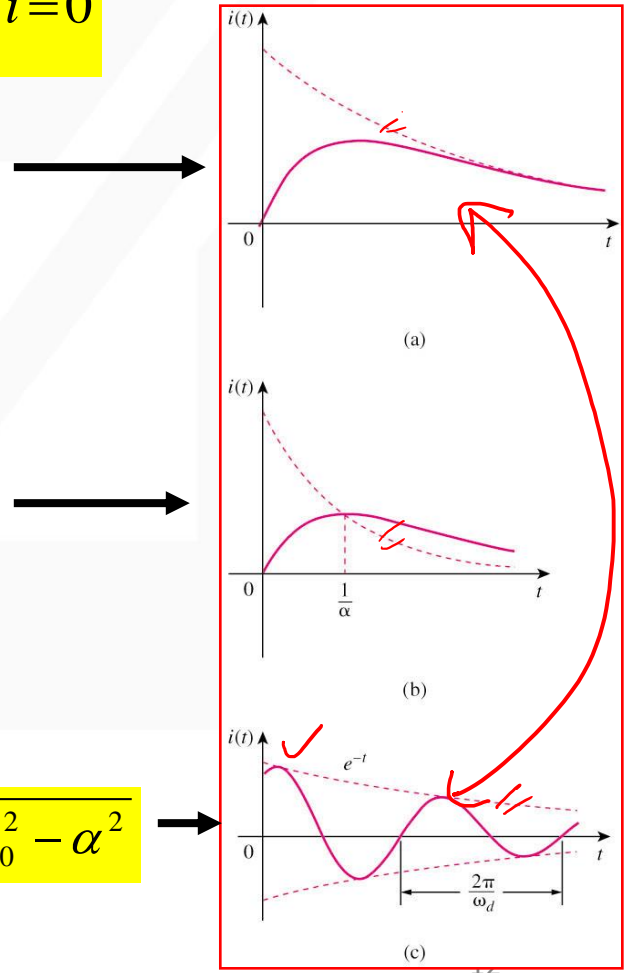
$$i(t) = Ae^{s_1 t} + Be^{s_2 t} \quad \text{where} \quad s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

2. If  $\alpha = \omega_0$ , critical damped case

$$i(t) = (A + Bt)e^{-\alpha t} \quad \text{where} \quad s_{1,2} = -\alpha$$

3. If  $\alpha < \omega_0$ , ~~under-damped~~ case

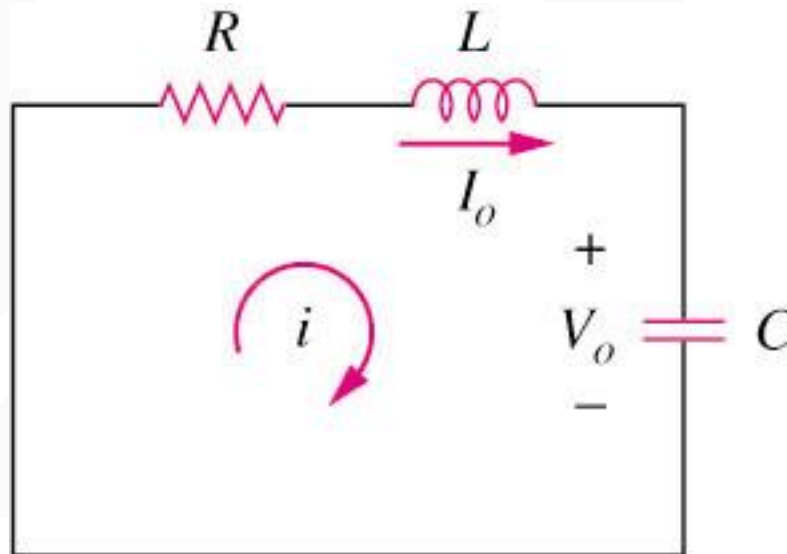
$$i(t) = e^{-\alpha t} (A \cos \omega_d t + B \sin \omega_d t) \quad \text{where} \quad \omega_d = \sqrt{\omega_0^2 - \alpha^2}$$



# 8.2 Source-Free Series RLC Circuits

## Example 1

If  $R = 10\Omega$ ,  $L = 5\text{H}$ , and  $C = 2\text{mF}$  in figure below, find  $\alpha$ ,  $\omega_0$ ,  $s_1$  and  $s_2$ . What type of natural response will the circuit have?



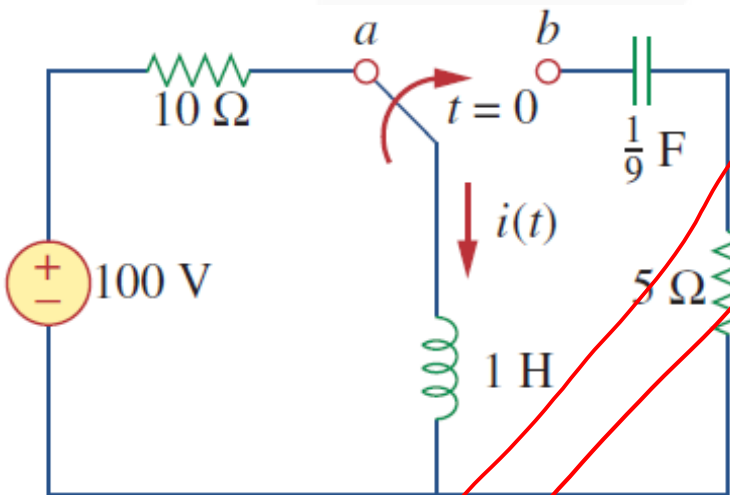
$$\alpha = \frac{R}{2L} = \frac{10}{2(5)} = 1$$

$$\omega_0 = \sqrt{\frac{1}{LC}} = \sqrt{\frac{1}{5(0.002)}} = 10$$

Answer: *underdamped*

# 8.2 Source-Free Series RLC Circuits

**Example 2** The circuit shown below has reached steady state at  $t=0^-$ . If the make-before-break switch moves to position b at  $t=0$ , calculate  $i(t)$  for  $t > 0$ .



$$\frac{di(0)}{dt} = -\frac{1}{L}(RI_0 + V_0) = -\frac{1}{1}(50 + 0) = -50$$

$$i(0) = I_0 = 10 \text{ A}$$

$$\alpha = \frac{R}{2L} = \frac{5}{2(1)} = 2.5$$

$$\omega_0 = \sqrt{\frac{1}{LC}} = \sqrt{\frac{1(9)}{1}} = 3$$

$$\omega_d = \sqrt{\omega_0^2 - \alpha^2} = \sqrt{3^2 - 2.5^2} = 1.6583$$

*underdamped*

$$i(t) = e^{-\alpha t} (A \cos \omega_d t + B \sin \omega_d t) = e^{-2.5t} (10 \cos(1.6583t) - 15.076 \sin(1.6583t)) \text{ A}$$

**Answer:**  $i(t) = e^{-2.5t} (10 \cos(1.6583t) - 15.076 \sin(1.6583t)) \text{ A}$

$$\frac{di(0)}{dt} = -\frac{1}{L}(RI_0 + V_0) = -\frac{1}{1}(50 + 0) = -50$$

$$i(0) = I_0 = 10A$$

$$-25 = 1.6583 B$$

$$B = \frac{-25}{1.6583} = -15.076$$

$$i(t) = e^{-2.5t} (A \cos \omega_d t + B \sin \omega_d t)$$

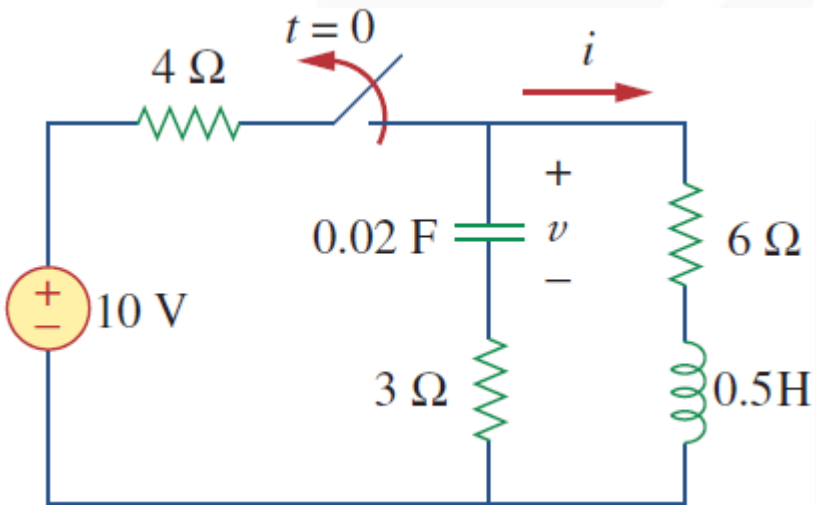
$$\frac{di(t)}{dt} = -50 = -2.5 e^{-2.5t} (A \cos \omega_d t + B \sin \omega_d t) + e^{-2.5t} (-A \omega_d \sin \omega_d t + B \omega_d \cos \omega_d t)$$

$$= -2.5(10 + 0) + (0 + B 1.6583)$$

$$i(t) = e^{-\alpha t} (A \cos \omega_d t + B \sin \omega_d t) = e^{-2.5t} (10 \cos(1.6583t) - 15.076 \sin(1.6583t))A$$

# 8.2 Source-Free Series RLC Circuits

Example 3 Find  $i(t)$  in the circuit of Figure below. Assume that the circuit has reached steady state at  $t=0^-$ .



$$\frac{di(0)}{dt} = -\frac{1}{L}(RI_0 + V_0) = -\frac{1}{0.5}(9 - 6) = -6$$

$$i(0) = I_0 = 1\text{A}$$

$$\alpha = \frac{R}{2L} = \frac{9}{2(0.5)} = 9$$

$$\omega_0 = \sqrt{\frac{1}{LC}} = \sqrt{\frac{1}{0.5(0.02)}} = 10$$

$$\omega_d = \sqrt{\omega_0^2 - \alpha^2} = \sqrt{10^2 - 9^2} = 4.3589$$

*underdamped*

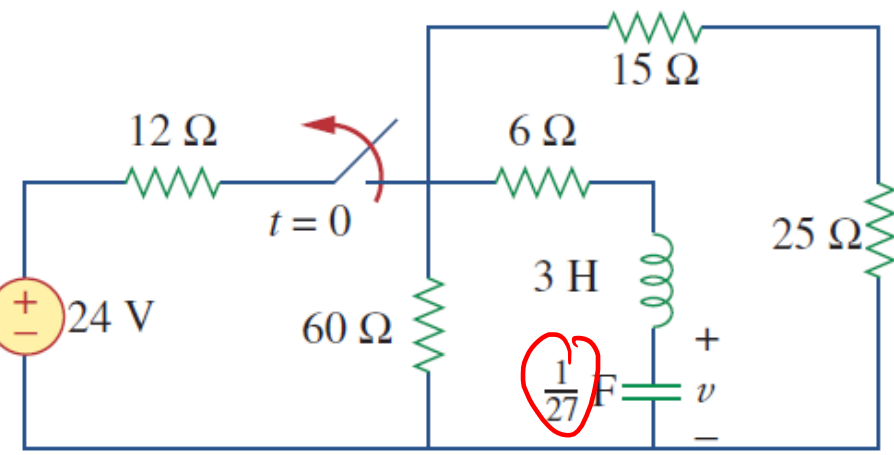
$$i(t) = e^{-\alpha t} (A \cos \omega_d t + B \sin \omega_d t) = e^{-9t} (1 \cos(4.3589t) + 0.6882 \sin(4.3589t))\text{A}$$

Answer:  $i(t) = e^{-9t} (\cos(4.3589t) + 0.6882 \sin(4.3589t))\text{A}$



# 8.2 Source-Free Series RLC Circuits

Example 4 Find  $v(t)$  for  $t > 0$



$$v(0) = V_0 = \left( \frac{24}{24+12} \right) 24 = 16V \quad i(0) = I_0 = 0$$

$$\alpha = \frac{R}{2L} = \frac{30}{2(3)} = 5$$

$$\omega_0 = \sqrt{\frac{1}{LC}} = \sqrt{\frac{27}{3}} = 3$$

overdamped

Handwritten:  $A = -\frac{2}{3}$   
 $B = -A = \frac{2}{3}$

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2} = -5 + \sqrt{5^2 - 3^2} = -1$$

$$s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2} = -5 - \sqrt{5^2 - 3^2} = -9$$

Handwritten:  $i = C \frac{dv}{dt}$   
 $i = Ae^{-t} - Ae^{-9t}$

$$v(t) = Ae^{-s_1 t} + Be^{-s_2 t} = Ae^{-t} + Be^{-9t}$$

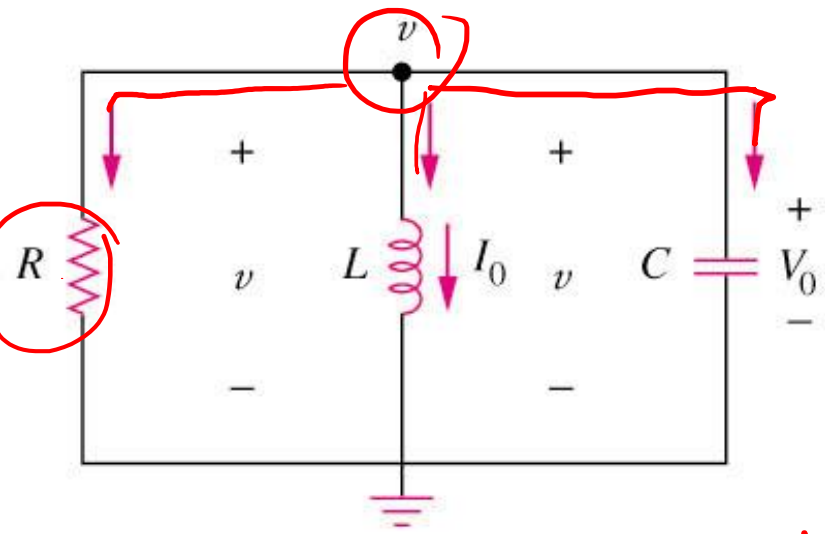
$$i(t) = C \frac{dv}{dt} = \frac{1}{27} (-Ae^{-t} - 9Be^{-9t})$$

Handwritten:  $v(0) = 16 = A + B$   
 $i(0) = 0 = \frac{1}{27} (-A - 9B) \rightarrow A = -9B$   
 $B = -2, A = 18$   
 $v(t) = 18e^{-t} - 2e^{-9t}$

Answer:

$$i(t) = \left( -\frac{2}{3} \right) e^{-t} + \left( \frac{2}{3} \right) e^{-9t}$$

# 8.3 Source-Free Parallel RLC Circuits



Let 
$$i(0) = I_0 = \frac{1}{L} \int_{-\infty}^0 v(t) dt$$

$v(0) = V_0$ , Apply KCL to the top node:

$$\frac{1}{R} \frac{dv}{dt} + \frac{v}{L} + C \frac{d^2 v}{dt^2} = 0$$

$$\frac{v}{R} + \frac{1}{L} \int_{-\infty}^t v dt + C \frac{dv}{dt} = 0$$

Taking the derivative with respect to  $t$  and dividing by  $C$

**The 2<sup>nd</sup> order of expression**

$$\frac{d^2 v}{dt^2} + \frac{1}{RC} \frac{dv}{dt} + \frac{1}{LC} v = 0$$

# 8.3 Source-Free Parallel RLC Circuits

There are 3 possible solutions for the following 2<sup>nd</sup> order differential equation:

$$\frac{d^2v}{dt^2} + 2\alpha \frac{dv}{dt} + \omega_0^2 v = 0 \quad \text{where} \quad \alpha = \frac{1}{2RC} \quad \text{and} \quad \omega_0 = \sqrt{\frac{1}{LC}}$$

1. If  $\alpha > \omega_0$ , over-damped case

$$v(t) = A e^{s_1 t} + B e^{s_2 t} \quad \text{where} \quad s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

2. If  $\alpha = \omega_0$ , critical damped case

$$v(t) = (A + Bt) e^{-\alpha t} \quad \text{where} \quad s_{1,2} = -\alpha$$

3. If  $\alpha < \omega_0$ , under-damped case

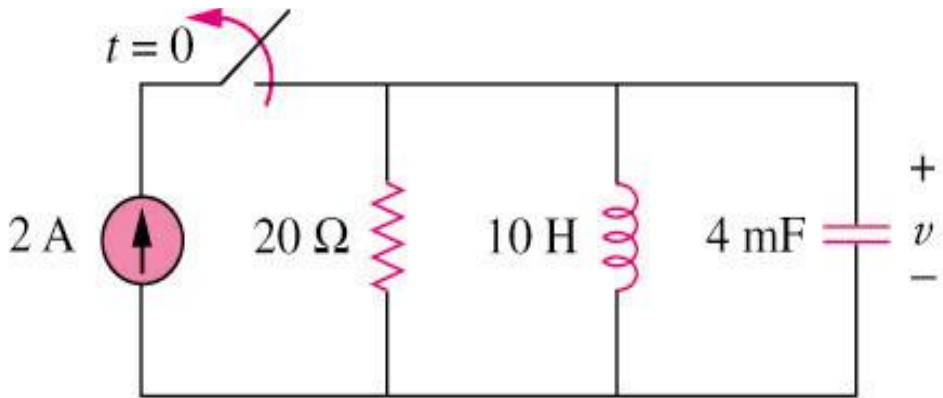
$$v(t) = e^{-\alpha t} (A \cos \omega_d t + B \sin \omega_d t) \quad \text{where} \quad \omega_d = \sqrt{\omega_0^2 - \alpha^2}$$

$$s_{1,2} = -\alpha \pm i\omega_d$$

*Handwritten notes:*  
 $s_{1,2} = -\alpha \pm \sqrt{(-1)(\omega_0^2 - \alpha^2)}$   
 $= -\alpha \pm \omega_d \sqrt{-1}$   
 $= -\alpha \pm i\omega_d$

# 8.3 Source-Free Parallel RLC Circuits

**Example 5** Refer to the circuit shown below. Find  $v(t)$  for  $t > 0$ .



$$v(0) = 0, i(0) = 2$$

$$\alpha = \frac{1}{2RC} = \frac{1}{2(20)(0.004)} = 6.25$$

$$\omega_0 = \sqrt{\frac{1}{LC}} = \sqrt{\frac{1}{10(0.004)}} = 5$$

*overdamped*

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} = -6.25 \pm \sqrt{6.25^2 - 5^2} = -6.25 \pm 3.75 = -2.5, -10$$

$$v(t) = A e^{s_1 t} + B e^{s_2 t} = A e^{-2.5t} + B e^{-10t} \quad v(0) = 0 = A + B$$

$$v(t) = L \frac{di}{dt} \rightarrow i = \frac{1}{L} \int v(t) dt \rightarrow i(t) = \frac{1}{10} \int (A e^{-2.5t} + B e^{-10t}) dt \quad i(0) = 2 = -\frac{A}{25} - \frac{B}{100}$$

$$B = \frac{200}{3}, A = -\frac{200}{3}$$

*Handwritten notes:*  
 $\frac{200}{3}$   
 $\frac{200}{3}$   
 $-2.5t$   
 $-10t$

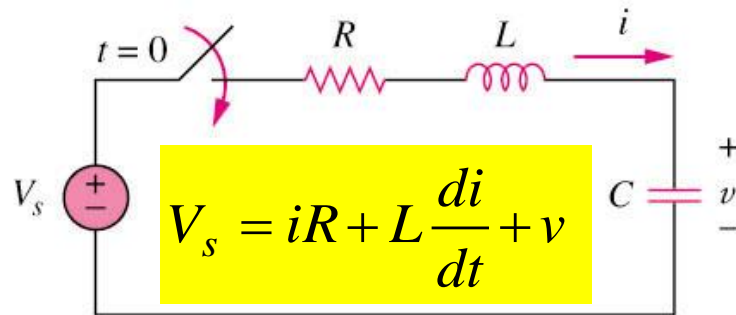
$$v(t) = \frac{200}{3} (e^{-10t} - e^{-2.5t})$$

$$\rightarrow v(t) = A e^{-2.5t} - A e^{-10t}$$

Answer:

# 8.4 Step-Response Series RLC Circuits

The step response is obtained by the sudden application of a dc source.



$$V_s = iR + L \frac{di}{dt} + v$$

$$i = C \frac{dv}{dt}$$

$$V_s = RC \frac{dv}{dt} + LC \frac{d^2 v}{dt^2} + v$$

**The 2<sup>nd</sup> order of expression**

$$\frac{d^2 v}{dt^2} + \frac{R}{L} \frac{dv}{dt} + \frac{v}{LC} = \frac{V_s}{LC}$$

The above equation has the same form as the equation for source-free series RLC circuit.

- The same coefficients (important in determining the frequency parameters).
- Different circuit variable in the equation.

# 8.4 Step-Response Series RLC Circuits

The solution of the equation should have two components:

the transient response  $v_t(t)$  & the steady-state response  $v_{ss}(t)$ :

$$v(t) = v_t(t) + v_{ss}(t)$$

- The transient response  $v_t$  is the same as that for source-free case

$$v_t(t) = Ae^{s_1 t} + Be^{s_2 t}$$

(over-damped)

$$v_t(t) = (A + Bt)e^{-\alpha t}$$

(critically damped)

$$v_t(t) = e^{-\alpha t} (A \cos \omega_d t + B \sin \omega_d t)$$

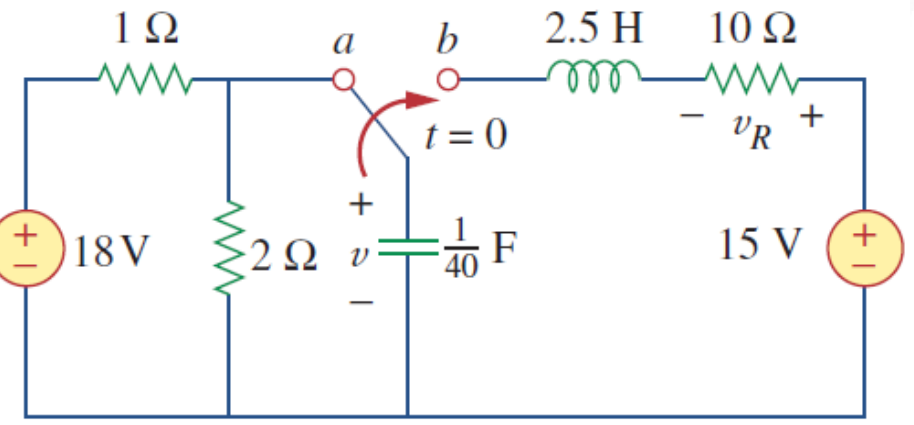
(under-damped)

- The steady-state response is the final value of  $v(t)$ .  $v_{ss}(t) = v(\infty)$

- A and B are obtained from the initial conditions :  $v(0)$  ,  $\frac{dv(0)}{dt}$

# 8.4 Step-Response Series RLC Circuits

Example 6 Having been in position for a long time, the switch in the circuit below is moved to position b at  $t=0$ . Find  $v(t)$  and  $v_R(t)$  for  $t > 0$ .



$$v(0) = \frac{2}{3}(18) = 12V, \quad i(0) = 0$$

$$v_{ss}(t) = 15, \quad i(0) = C \frac{dv(0)}{dt} \rightarrow \frac{dv(0)}{dt} = 0$$

$$\alpha = \frac{R}{2L} = \frac{10}{2(2.5)} = 2, \quad \omega_0 = \sqrt{\frac{1}{LC}} = \sqrt{\frac{40}{2.5}} = 4$$

$$\omega_d = \sqrt{\omega_0^2 - \alpha^2} = 2\sqrt{3} \quad \text{under-damped}$$

$$v(t) = v_{ss}(t) + v_t(t) = 15 + e^{-2t} (A \cos 2\sqrt{3}t + B \sin 2\sqrt{3}t) \quad v(0) = 12 = 15 + A \rightarrow A = -3$$

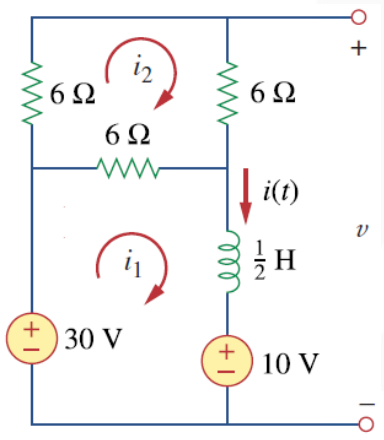
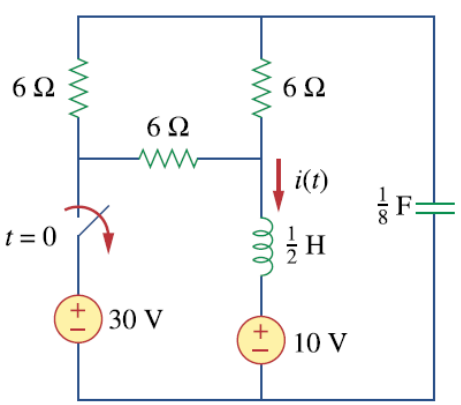
$$\frac{dv(t)}{dt} = \left( -2e^{-2t} (-3 \cos 2\sqrt{3}t + B \sin 2\sqrt{3}t) \right) + \left( e^{-2t} (6\sqrt{3} \sin 2\sqrt{3}t + 2\sqrt{3}B \cos 2\sqrt{3}t) \right)$$

$$\frac{dv(0)}{dt} = 0 = 6 + 2\sqrt{3}B \rightarrow B = -\sqrt{3}$$

Answer:  $v(t) = 15 - e^{-2t} (3 \cos(2\sqrt{3}t) + \sqrt{3} \sin(2\sqrt{3}t))V : v_R(t) = 2\sqrt{3}e^{-2t} \sin(2\sqrt{3}t)V$

# 8.4 Step-Response Series RLC Circuits

Example 7 Find  $i(t)$  in the circuit of Figure below.



$$i(0) = I_0 = 5A \quad i_1 = 5A, \quad i_2 = \frac{5}{3}A, \quad v(0) = 20V$$

$$R = 12 // 6 = 4\Omega, \quad \alpha = \frac{R}{2L} = \frac{4(2)}{2} = 4$$

$$\omega_0 = \sqrt{\frac{1}{LC}} = \sqrt{16} = 4, \quad \text{critically-damped}$$

$$v(t) = v_{ss}(t) + v_t(t) = 10 + e^{-4t}(A + Bt)$$

$$v(0) = 20 = 10 + A \rightarrow A = 10$$

$$i(0) = -5 = \frac{e^{-4t}}{8}(-4(A + Bt) + B)$$

$$B = 0$$

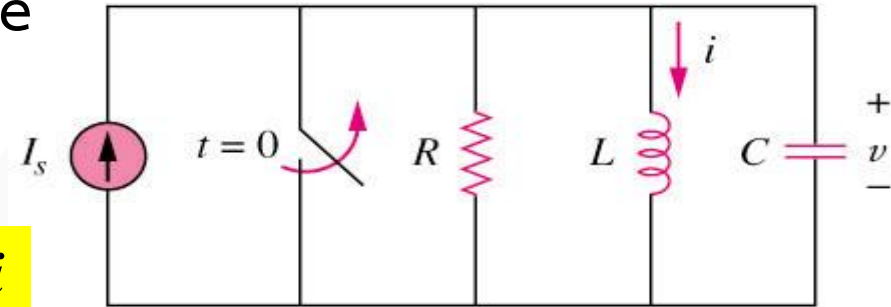
$$i(t) = -C \frac{dv}{dt} = \frac{e^{-4t}}{8}(40) = 5e^{-4t}$$

Answer:  $i(t) = 5e^{-4t}$



# 8.5 Step-Response Parallel RLC Circuits

The step response is obtained by the sudden application of a dc source.



$$C \frac{dv}{dt} + \frac{v}{R} + i = I_s$$

$$v = L \frac{di}{dt}$$

$$LC \frac{d^2 i}{dt^2} + \frac{L}{R} \frac{di}{dt} + i = I_s$$

**The 2<sup>nd</sup> order of expression**

$$\frac{d^2 i}{dt^2} + \frac{1}{RC} \frac{di}{dt} + \frac{i}{LC} = \frac{I_s}{LC}$$

It has the same form as the equation for source-free parallel RLC circuit.

- The same coefficients (important in determining the frequency parameters).
- Different circuit variable in the equation.

# 8.5 Step-Response Parallel RLC Circuits

The solution of the equation should have two components:

the transient response  $v_t(t)$  & the steady-state response  $v_{ss}(t)$ :

$$i(t) = i_t(t) + i_{ss}(t)$$

- The transient response  $i_t$  is the same as that for source-free case

$$i_t(t) = Ae^{s_1t} + Be^{s_2t} \quad (\text{over-damped})$$

$$i_t(t) = (A + Bt)e^{-\alpha t} \quad (\text{critical damped})$$

$$i_t(t) = e^{-\alpha t} (A \cos \omega_d t + B \sin \omega_d t) \quad (\text{under-damped})$$

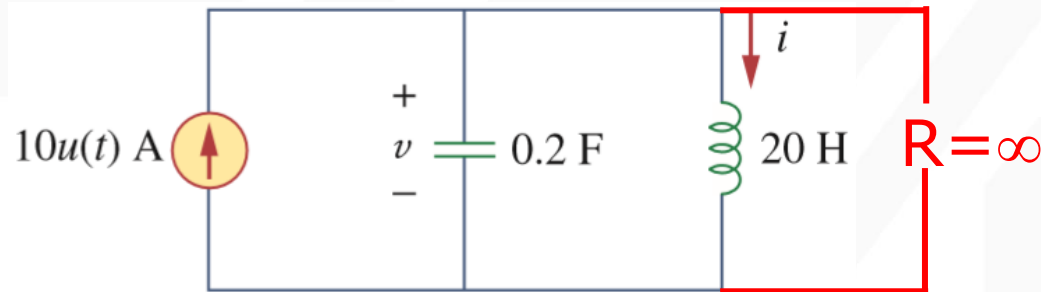
- The steady-state response is the final value of  $i(t)$ .  $i_{ss}(t) = i(\infty) = I_s$

- The values of A and B are obtained from the initial conditions:  $i(0)$ ,  $\frac{di(0)}{dt}$

# 8.5 Step-Response Parallel RLC Circuits

## Example 8

Find  $i(t)$  and  $v(t)$  for  $t > 0$  in the circuit shown in circuit shown below:



$$\alpha = \frac{1}{2RC} = 0, \omega_0 = \frac{1}{\sqrt{LC}} = 0.5, \omega_0 = \omega_d$$

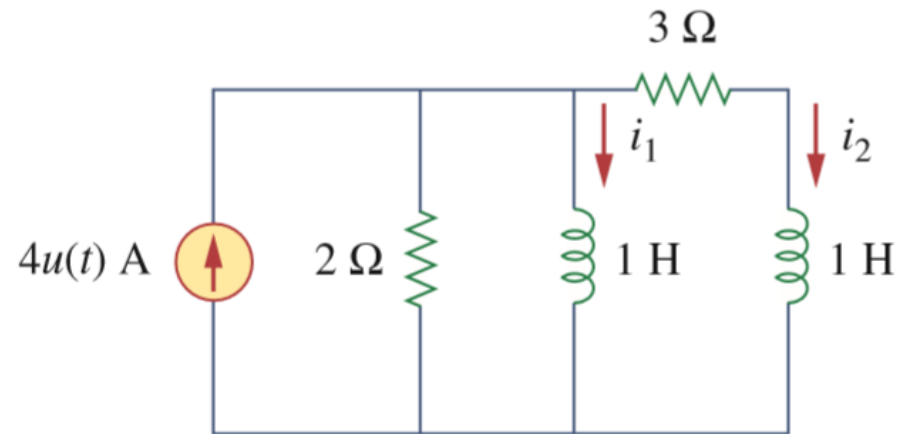
$$i_t(t) = e^{-\alpha t} (A \cos \omega_d t + B \sin \omega_d t)$$

$$i(t) = A \cos \omega_d t + B \sin \omega_d t$$

Answer:  $10(1 - \cos(0.25t))$  A,  $50 \sin(0.25t)$  V.

# 8.5 Step-Response Parallel RLC Circuits

Example 9 Find  $i_1$  and  $i_2$  for  $t > 0$



$$\text{At } t = 0^-, 4u(t) = 0 \text{ so that } i_1(0) = 0 = i_2(0) \quad (1)$$

Applying nodal analysis,

$$4 = 0.5di_1/dt + i_1 + i_2 \quad (2)$$

$$\text{Also, } i_2 = [1di_1/dt - 1di_2/dt]/3 \text{ or } 3i_2 = di_1/dt - di_2/dt \quad (3)$$

$$\text{Taking the derivative of (2), } 0 = d^2i_1/dt^2 + 2di_1/dt + 2di_2/dt \quad (4)$$

$$\begin{aligned} \text{From (2) and (3), } di_2/dt &= di_1/dt - 3i_2 = di_1/dt - 3(4 - i_1 - 0.5di_1/dt) \\ &= di_1/dt - 12 + 3i_1 + 1.5di_1/dt \end{aligned}$$

# 8.5 Step-Response Parallel RLC Circuits

Substituting this into (4),

$$d^2i_1/dt^2 + 7di_1/dt + 6i_1 = 24 \text{ which gives } s^2 + 7s + 6 = 0 = (s + 1)(s + 6)$$

$$\text{Thus, } i_1(t) = I_s + [Ae^{-t} + Be^{-6t}], \quad 6I_s = 24 \text{ or } I_s = 4$$

$$i_1(t) = 4 + [Ae^{-t} + Be^{-6t}] \text{ and } i_1(0) = 4 + [A + B] \tag{5}$$

$$i_2 = 4 - i_1 - 0.5di_1/dt = i_1(t) = 4 + -4 - [Ae^{-t} + Be^{-6t}] - \frac{[-Ae^{-t} - 6Be^{-6t}]}{2}$$

$$= [-0.5Ae^{-t} + 2Be^{-6t}] \text{ and } i_2(0) = 0 = -0.5A + 2B \tag{6}$$

From (5) and (6),

$$A = -3.2 \text{ and } B = -0.8$$

$$i_1(t) = \underline{\{4 + [-3.2e^{-t} - 0.8e^{-6t}]\} A}$$

$$i_2(t) = \underline{[1.6e^{-t} - 1.6e^{-6t}] A}$$